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SENSITIVITY OF THE ERROR IN
MULTIVARIATE STATISTICAL INTERPOLATION
TO PARAMETER VALUES

by

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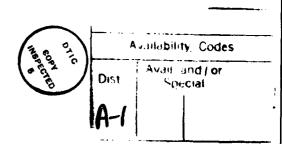
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#### 1.0 INTRODUCTION

The purpose of this study is to document the sensitivity of multivariate statistical interpolation to the values of statistical parameters, misspecification of these parameters, and to missing observations. It is hoped that this information will enable practitioners to concentrate on the appropriate specification of crucial parameters while avoiding agony over those that have relatively small effect. The results presented here point out some interesting dependencies which I believe have not been previously published. Prior studies upon which this work builds are Franke (1985 and 1988) and especially Franke, et It was also influenced by Seaman (1983). al. (1988). previous studies, however, involved only univariate objective analysis schemes. While many of the results can be expected to carry over in a similar way, the influence of wind observations on the expected error over various observation sets is useful and interesting. Further, I believe that the graphical presentation of the results used here makes it easy to discern the important parameters.

A brief overview of multivariate statistical interpolation and the method used to calculate expected errors is given in Section 2. The details of the necessary calculations are not given explicitly there, but are available in Appendix 2, which gives a listing of the subroutine used to evaluate the covariance matrices. Section 3 gives a discussion of the various parameters and the values over which they were varied during the study. Section 4 contains an analysis of the results. Because of the plethora of data which was generated it is difficult to comprehend the important details in tabular format, and therefore the information is incorporated into a few graphs which enable one to easily ascertain the sensitivities of the scheme to the various parameters. Tables are included in Appendix 1 for completeness, but it is expected that few readers will find them necessary. Section 5 contains the concluding remarks.



#### 2.0 MULTIVARIATE STATISTICAL INTERPOLATION

Statistical Interpolation (SI) is in use at many of the world's Numerical Weather Prediction (NWP) facilities, including the U.S. Navy's Fleet Numerical Oceanography Center (FNOC). The scheme has its roots in the work of Kolmogorov and Weiner, and was first developed for meteorological applications by Gandin (1965). More recently it has been applied in multivariate form by Schlatter (1975), Schlatter, et al. (1976), Bergman (1979), and Lorenc (1981).

In its perfect form (all parameters known), SI delivers estimates of a field with minimum mean squared error over a certain ensemble of realizations that satisfy normality and stationarity of the underlying stochastic process. For convenience, isotropy is usually assumed, and for meteorological problems a zero mean is assumed (although a nonzero mean can be accounted for in more than one way).

In the multivariate formulation, the dependent data consists of related variables, which in our case we assume to be the errors in the background pressure height and wind fields, H, U, and V, as related through the geostrophic relationship:

$$u = k_1 H_x, \quad v = k_2 H_y.$$

Here the values of  $k_1$  and  $k_2$  are dependent on the latitude. The SI equations are applied to the background error, obtained by forming the difference between the background (normally the NWP values, interpolated to the observation locations) and the observed values. The assumption of normality implies the minimum variance (or least mean squared error) predictor is a linear combination of the data values. Then construction of the weights leads to solution of a system of equations whose coefficient matrix is the matrix of spatial covariances and cross-covariances for the variables. Because of the assumed relationship between the variables, the wind error covariances and the cross-covariances are determined when the height error spatial covariance function is known. The exact relationship is given in

Franke, et al. (1988), as well as in other references above.

The SI equations have been derived in numerous places (see e.g., Schlatter (1975), Lorenc (1981), Thiébaux (1985), and Thiébaux and Pedder (1987)) and are repeated here only for completeness. Let  $\mathbf{O} = \{\mathbf{o}_j\}_{j=1}, \dots, \mathbf{N}$  represent N measured values, with corresponding independent observation error variance (diagonal) matrix  $\mathbf{\Sigma} = \{\sigma_j^2\}$ ,  $\mathbf{B} = \{\mathbf{b}_j\}$  the corresponding vector of background values, and  $\mathbf{C} = \{\mathbf{c}_{i,j}\}_{i,j=1}, \dots, \mathbf{N}$  the spatial covariance matrix for the background errors. Then, letting  $\mathbf{C}_0 = \{\mathbf{c}_{0,j}\}_{j=1}, \dots, \mathbf{N}$  denote the vector of covariances between the error in the variable at the location  $\mathbf{P}_0$  at which it is to be analyzed and the background errors, the following equation holds for the analyzed value,  $\mathbf{a}_0$ :

$$a_0 = b_0 + c_0^T (C+\Sigma)^{-1} (O - B)$$
.

If the statistical parameters are known precisely (whereupon SI becomes Optimum Interpolation, or OI), then the expected error variance for the estimated variable at  $P_0$  is given in the usual least squares form,

$$\sigma_0^2 = \sigma_b^2 - c_0^T (c+\Sigma)^{-1} c_0^{\phantom{T}},$$

where  $\sigma_{\rm b}^2$  is the variance of the background error. Considering the case where the statistical parameters are not known exactly, the analyzed value becomes

$$a_0 = b_0 + \tilde{c}_0^T (\tilde{c} + \tilde{\Sigma})^{-1} (O - B) ,$$

where the tilde overbar signifies assumed inexact values. Notice that the equation is exactly the same except that assumed values replace the exact values for covariances. The expected mean squared error is

$$\sigma_0^2 = \sigma_b^2 - 2c_0^T (\tilde{c} + \tilde{\Sigma})^{-1} \tilde{c}_0 + \tilde{c}_0^T (\tilde{c} + \tilde{\Sigma})^{-1} (c + \tilde{\Sigma}) (\tilde{c} + \tilde{\Sigma})^{-1} \tilde{c}_0.$$

These equations are given in Seaman (1983), where the vector  $\tilde{\mathbf{W}}_0 = (\tilde{\mathbf{C}} + \tilde{\mathbf{\Sigma}})^{-1} \tilde{\mathbf{C}}_0$  is interpreted in the usual statistical fashion, as the weight vector for the observed minus background values. This also simplifies the writing of the error expression and indicates a computationally efficient algorithm.

The expected error will be computed at a number of locations, in our case on a 7x11 grid of points. The matrix  $(\tilde{\mathbf{C}}+\tilde{\boldsymbol{\Sigma}})$  is symmetric and positive definite, so the computation of  $\tilde{\mathbf{W}}_0$  is accomplished by performing a one time Cholesky decomposition of  $(\tilde{\mathbf{C}}+\tilde{\boldsymbol{\Sigma}})$  into  $\mathbf{LL}^T$ , followed by forward and backward substitutions to find  $\tilde{\mathbf{W}}_0$  as the solution of  $\mathbf{LL}^T\mathbf{W}_0=\tilde{\mathbf{C}}_0$ . This is an important concept since the number of equations is the number of observations (up to 108 here), and  $\mathbf{P}_0$  varies over 77 locations in our case. In actual practice  $\mathbf{P}_0$  would vary over several locations for the same observation set when a block analysis scheme is used.

#### 3.0 SETTING FOR THE STUDY

An empirical study such as this one requires a number of compromises concerning the range of parameters permitted. In previous studies (Franke, 1985, and Franke, et al., 1988) a set of three grids and corresponding observation locations based approximately on the radiosonde network over the United States and the Atlantic Ocean were used. The study here is also at a single level. One difference from my previous studies, which has a rather minor influence, is that distances are measured in meters (approximately; I did not use the exact geodesic distance) rather than degrees. The formula used for the distance (also used by Schlatter (1975)) between two points ( $\theta$  = longitude,  $\varphi$  = latitude) is

$$d_{ij}^2 = r^2[(\varphi_j - \varphi_i)^2 + (\theta_j - \theta_i)^2 \cos^2(\frac{\varphi_j - \varphi_i}{2})]$$
.

While computed distances are (relatively) quite different in the upper latitudes, the overall influence on the expected mean squared errors is rather small over the regions we consider.

Figures 1-3 show the 2.5° grids and observation locations used in this study. The +'s indicate the grid points, while the small squares and circles represent the observation locations. The shaded circle represents the "missing observation" for tests of sensitivity of the analyzed values to one missing observation (both missing wind only and missing height and wind). The open circles represent additional missing observation locations for tests of sensitivity to many (one-half) missing observations. Each grid is a 7x11 grid of points, taken to be the interior grid points of a 9x13 grid containing the observation locations. The Middle United States (MUS) grid has 36 observations, the East Coast (EC) grid has 25 observation locations, while Middle Atlantic (MA) grid has only 3 observations.

The assumed correlation function for the height errors is the specialized second order autoregressive function (SOAR) that seems to be quite stable with respect to variations in the parameters while embodying enough parameters to fit historical data (Franke, et al., 1988). As noted by Thiébaux, et al. (1986), Balgovind, et al. (1983), the SOAR seems to have an affinity for meteorological data. The form we used is

$$C(s) = (1-\lambda)(1+as)e^{-as} + \lambda,$$

where s denotes the distance, and a and A are parameters which in practice are determined by a fitting process. In the previous section  $c_{ij}=C(d_{ij})\sigma_b^2$ , where  $d_{ij}$  is the distance between the i<sup>th</sup> and j<sup>th</sup> observation points. The study conducted here made use of five different sets of parameter values, as shown in Table 1, and also depicted in Figure 4. The "nominal" correlation function is considered to be #4, which approximates the Bessel function curve of Lonnberg (1982) closely, and also corresponds closely to the decay rate used by Lorenc and Hammon (1988). Varying from one correlation function to the next makes it possible to determine whether the additive constant or the decay rate constant is the more critical.

Cor#	A	a	#m to #m+1
1	0.0	5.000x10 <sup>-6</sup>	
2	0.0	3.082x10 <sup>-6</sup>	a decreases
3	0.15	3.082x10 <sup>-6</sup>	A increases
4	0.2722	3.082x10 <sup>-6</sup>	A increases
5	0.2722	2.188x10 <sup>-6</sup>	a decreases

Table 1: Correlation Functions

The nominal value for the standard deviation of the background height error is 30 m. The correlation function then determines the variance of the wind field errors, and the standard deviations for wind errors are given in Table 2. Because the values of  $\mathbf{k}_1$  and  $\mathbf{k}_2$  depend on the latitude, the rms errors over a given grid depend on the grid. All expected wind errors were calculated relative to their value at a given point, and the rms values of these are given in the tables and the figures, different than computing the expected rms values over the grid and then comparing this with the rms background error over the grid.

The nominal values assumed for the observation errors were 10 m for heights and 1.0 m/sec for wind components. For OI these values were varied over the values 0, 5, 10, 20, and  $\infty$  m for heights, and 0, 0.5, 1.0, 2.0, and  $\infty$  m/sec for the winds. The expected rms error was not computed for all combinations of these values; the  $\infty$  values imply no measurement of that variable and computations were only performed with the nominal value of the other measurement error, for example. These calculations were performed with OI to show the effect of no observations of a particular variable. With no wind observations, the process collapses to the usual univariate OI scheme.

In order to assess the effect of missing observations, four "missing observation" computations were performed. For one observation point in each grid it was assumed that the wind

observations were not available; then it was assumed that the height observation at the same location was not available. For about one-half of the observation points it was assumed that the wind observations were not available; then it was assumed that the corresponding height observations were not available.

The computations of expected rms errors for the statistical schemes did not cover such a wide range of assumed observation error values. Variations of the assumed observation errors and spatial correlation function number were only carried out to the adjacent value (assumed observation error changing by a factor of .5 or 2, and correlation function number only to the adjacent number).

Cor#	grid 1&2	grid 3
1	16.05	14.52
2	9.89	8.95
3	9.12	8.25
4	8.44	7.64
5	5.99	5.42

Table 2: Background wind errors, m/sec

### 4.0 ANALYSIS OF THE RESULTS

The easy detection of the sensitivity to parameters on which a process depends is sometimes clouded by the mass of information available. In the following, I believe the plotting scheme adopted enables readers to easily detect critical parameters.

In this study there are four important parameters that are varied for each of the three grids: The height observation accuracy, the wind observation accuracy, the additive constant A in the correlation function, and the decay rate a (the reciprocal can be thought of as some measure of "correlation distance") in the correlation function. In this study the correlation function

paramethis have not been varied except one at a time, in the manner noted in the previous section.

We first consider the sensitivity of OI to the accuracy of the observations. The results for the error in the analyzed height field for 13 different combinations of observation accuracies and 5 correlation functions are shown in Figures 5-7 for the MUS, EC, and MA grids, respectively. Note that only the integer abscissa values have meaning, and the points are connected only to enable one to more easily see the effects of changing parameter values. As one moves to the right on the scale, the trend is toward less observation accuracy, with wind observation accuracies first decreasing, while the height observation accuracy more slowly decreases. From the plots, it is seen that significant increases in OI height analysis errors occur at abscissae 2, 5, 9, and 13, while between there is generally some increase, but much smaller in magnitude. lists the values of the observation accuracies, and it is seen that for 2, 5, 10, and 13 there are jumps in the observation accuracy for heights. The jump in expected error at abscissa 9 is due to the complete loss wind observations, and if this abscissa is omitted, then the jump would be due to the height accuracy change at abscissa 10. From this graph it is apparent that the accuracy of height observations are of premier importance in the height analysis, while the accuracy of the wind observations are less important in the nominal range considered here, except that not having wind observations at all also results in a significant increase in OI error.

Significant increases in error of the analyzed height field are seen to occur with decreasing correlation distance (increasing value of a) and decreasing constant A, for all three grid and observation point sets. Of course, the effects of observation accuracy are considerably smaller for the sparse MA grid. For all three grids it is apparent that OI errors are more sensitive to changes in the correlation distance (parameter a) than in the additive constant A.

abscissa	h error	w error
1	0	1.0
2	5	0.5
3	5	1.0
4	5	2.0
5	10	0.0
6	10	0.5
7	10	1.0
8	10	2.0
9	10	<b>∞</b>
10	20	0.5
11	20	1.0
12	20	2.0
13	∞	1.0

Table 3: Abscissa key for Figures 5-16

The corresponding plots for the errors in the analyzed wind fields are shown in Figures 8-10. The errors shown are the rms of the two winds, the values generally being quite close together, as can be seen by referring to Tables 1.g.m in the Appendix 2. The errors in the analyzed wind fields generally follow the same trend as the errors in the analyzed height fields, except that the wind errors are more sensitive to the wind observation errors, this being especially prominent when there are no wind observations (at abscissa 9). One interesting thing to notice is that the curves for correlation functions 2-4 are very close together, indicating an even greater dependence on the decay rate parameter, a, than the analyzed height errors exhibited.

In order to assess the importance of a single observation and the effects of many missing observations, some OI analysis errors were computed based on missing observed values. The missing observations are shown in Figures 1-3 for the three grids. The expected OI height analysis errors are shown in Figures 11-13 for the three grids, and the expected OI wind analysis errors in Figures 14-16. I will discuss Figure 11 in some detail, and a similar analysis follows for the other figures.

The figure is slightly busy. The open circles and open

squares denote the values for correlation functions #4 and #1, respectively, the same values as given in Figure 5. The same symbol with the + denotes the analyzed values under the same assumptions but with observed values missing (appearing twice; once with observation of winds missing at the location noted previously, the second with observations of both winds and height missing). It can be noted that the missing wind observation is nearly undetectable while there is only a slight degradation with the height observation also missing. This is, however, more prominent in the case of smaller correlation in the upper graph for correlation function #1. The shaded symbols denote the values obtained when one-half (18) of the observations are missing (again, twice, once for missing winds, and once for missing heights and winds). At abscissa 9 the symbol overlays the others for which there are no wind observations and height observations at all locations. The nominal case (abscissa 7) shows about a 15 percent increase in the analysis errors when 18 wind observations are missing, and about a 50 percent increase in the analysis errors for each correlation function when the entire observation is missing at 18 points. In this case, a 15 percent increase in the analysis errors corresponds to about a 6 percent decrease in "skill", where "skill" is taken as (1 - expected analysis error relative to background error), and the 50 percent increase in error to about a 20 percent decrease in skill. The general pattern of error for the various parameter values is generally the same as for that obtained for the entire observation set, the primary difference being for abscissa 9 where the wind observations are all missing.

The OI analyzed height error for the EC grid (Figure 12) follows much the same pattern, except that the increase due to one missing observation is somewhat more significant, the total number of observations being 25 instead of 36 as in the MUS grid. Again, with one-half the observations missing, the error is increased by about 50 percent, and the drop in skill about 25 percent.

The MA grid results in Figure 13 differ since one missing

observation is nearly one-half of the total of three. Thus there are no shaded symbols in that figure, and a completely missing observation results in an increase of height analysis error of a few percent, but this again being about a 20 percent drop in skill.

The plots for the wind analysis errors are given in Figures 14-16. Note that some of symbols for separate correlation functions are overlaid in Figures 14 and 15. Of course, the wind analysis is sensitive to the loss of one or more observations, with the increase in wind analysis errors in Figure 14 for the MUS grid showing an increase of about 6-8 percent with 18 missing wind observations, and about 12-15 percent when the entire observation is missing at 18 points. The decrease in skill here corresponds to about 20 percent and 40 percent, respectively. On a relative basis the analysis errors are significantly larger for winds, with smaller relative increases in the error when observations are missing, however, in terms of skill level, the winds are more dependent on the observations. Again, the general character of the errors follows the same pattern, with the exception of abscissa 9, corresponding to no wind observations.

The plots for the wind analysis errors for the EC grid in Figure 15 and the MA grid in Figure 16 reveal no surprises. The general pattern of Figure 15 is similar to Figure 14, while Figure 16 reveals that a very small skill is involved in this case, so missing observations have little affect.

Unfortunately, none of the parameters varied above are really at the disposal of the practitioner. Still, the above information is a useful aid to understanding the OI (and SI) process and how achievable accuracy is affected by the parameters in the process.

The more important practical information is that given in Figures 17-22. Once again, the analysis errors are plotted versus a single abscissa which corresponds to various combinations of assumed parameter values. The nominal background rms error is 30 m for the height, as noted in the previous section, with the background wind errors depending on the

correlation function. Nominal height observation accuracy is 10 m, and nominal wind observation accuracy is 1 m/sec. For a given spatial correlation function number, the assumed observation accuracies and spatial correlation function are varied. Observation accuracies vary by a factor of .5 or 2 from the nominal, while correlation function number varies by at most one.

Consider Figure 17. The three "curves" for the MUS grid and spatial correlation functions 2, 3, and 4 will be discussed. in previous figures, only the integer abscissa values have meaning, and the points are connected only to enable one to more easily see the effects of changing parameter values. immediately apparent that the parameters to which the SI scheme are most sensitive are embodied in abscissae 9, 12, 13, and to a lesser extent, 2, 4, and 5. Table 4 shows the relationship between the abscissae and the parameter variations, and we see that each of these abscissae except 9 are for assumed height observation errors that are twice the nominal value, and abscissae 9, 12, and 13 are for a misspecified correlation function (greater correlation). Abscissa -8, -9, -10, -11, -12, and -13 also show relatively larger SI errors, and each of these abscissa are for low assumed correlation as well as improper assumed height observation error. It appears that it is better to underestimate height observation errors than to overestimate them, although there is a peak (but smaller) at abscissa -2, where the height observation error is underestimated.

Note that the graphs for correlation functions 3 and 4 are quite similar, while that for correlation function 2 differs somewhat for negative abscissae. Table 1 shows that the assumed correlation function (that is function 1) for large negative abscissae for correlation function 2 has a different decay rate, while for correlation functions 3 and 4, the decay rate is the same as that of 2 and 3. The relatively larger effect of the improper decay rate for the assumed correlation function is also

abscissa	h error	w erro	or   cor f.	#
	10	nominal		
<b> </b>	10		m	
i (		assumed	values	
-13	5	0.5	m-1	
-12	5	2	m-1	
-11	20	0.5	m-1	
-10	20	2	m-1	
-9	5	1	m-1	
-8	20	1	m-1	
-7	10	0.5	m-1	
<b>-</b> 6	10	2	m-1	
<b>-</b> 5	5	0.5	m	
-4	5	2	m	
-3	10	1	m-1	
-2	5	1	m	
-1	10	0.5	m	
0	10	1	m	
1	10	2	m	
2 3	20	1	m	
3	10	1	m+1	
4	20	2	m	
5	20	0.5	m	
6	10	2	m+1	
7	10	0.5	m+1	
8	20	1	m+1	
9	5	1	m+1	
10	5	0.5	m+1	
11	5	2	m+1	
12	20	0.5	m+1	
13	20	2	m+1	

Table 4: Abscissa key for Figures 17-22

apparent in the SI error for correlation function 4 at abscissae 9, 12, and 13, as noted above. Thus, the decay rate for the correlation function seems to be more important than the additive constant.

For the EC grid, the results shown in Figure 18 indicate that the character of the three graphs is much the same. The outstanding difference is the significantly larger SI errors occurring for correlation function #2 when the assumed correlation function is #1 (abscissae -3 and -6 to -13). Again, the graph for correlation function #4 shows larger SI errors for assumed correlation function #5 (larger abscissae). Both of

these cases correspond to misspecified decay rates. Looking higher to the MA grid, we see same effects: cases where the decay rate for the correlation function is misspecified yield larger increases in the SI height error than when the additive constant is misspecified.

The results for the MA grid shown in Figure 19 imply that the most crucial parameter to have correct in such sparse regions is the decay rate for the correlation function, unfortunately the most difficult to estimate in such cases. Further, it appears it is probably best to underestimate the decay rate in sparse (or semi-sparse regions, such as EC) regions. In data dense regions the height errors are generally less sensitive to misspecification of the correlation function (with the exception of this being in combination with overestimates of the height observation error).

The corresponding plots for SI wind errors are in Figures 20-22. Here the behavior of the errors seems to be less structured, with the smallest error often occurring for the correlation function corresponding to the least spatial correlation (SI height errors are generally a decreasing function of correlation function #). The behavior of the SI wind errors are also sensitive to the misspecification of the decay rate for the correlation function, as can be noted by the correlation function #2 values for large negative abscissae and for correlation function #4 for large positive abscissae. With that exception, the general behavior of the SI wind errors is much the same as for the SI height errors, with the primary dependence again being on the correct specification of the assumed height error.

One additional bit of information can be squeezed from the data generated by this study. This concerns the relationship between the expected error based on the OI calculations versus the actual expected error. Of course, since parameters are estimated, only the expected error for OI can be calculated when expected errors are needed (e.g., see Goerss (1989)). We give three examples to show how this proceeds, and to show the

variation in the values. While the information can also be obtained by looking at the appropriate figures, the information is more precisely and as easily obtained from the tables in Appendix 1.

- (1) Let us suppose that the assumed values of the observation errors are the twice the nominal ones and that the assumed spatial correlation function is #4. Height and wind observation errors equal 20 m and 2 m/sec, respectively. For the MUS grid the expected error for the heights (from Table 1.1.4, or Figure 5, abscissa 12 on Cor Ftn 4) is 0.3462. If the actual values for the observation errors are 10 m for heights and 1 m for winds, with spatial correlation function #3, then the actual expected error for the MUS grid is (from Table 6.1.3-4, or Figure 17, abscissa 13 on Cor Ftn 3) is 0.3092, significantly smaller than the OI calculation would indicate.
- (2) Now suppose the assumed values of the observation errors are one-half the nominal values and that the assumed correlation function is #3. Height and wind observation errors equal 5 m and 0.5 m/sec, respectively. For the MUS grid the expected error for the heights (from Table 1.1.3, or Figure 5, abscissa 2 on Cor Ftn 3) is 0.2291. Again if the correct values are the nominal values of 10 m and 1 m/sec for the height and wind observation errors, and the actual spatial correlation function is #4, then (from Table 6.1.4-3, or Figure 17, abscissa -13 on Cor Ftn 4) the correct expected error is 0.2819. In this case the expected errors are significantly larger than the OI calculation indicates.
- (3) In this case, suppose the spatial correlation function is correct, #4, and the assumed values of the observation errors are 5 m and 2 m/sec for heights and winds, respectively. Then the for the EC grid the expected height error (Table 1.2.4, or Figure 6, abscissa 4 on Cor Ftn 4) is 0.3486. If the actual observation errors are 10 m and 1 m/sec for heights and winds, respectively, then the actual expected error (Table 6.2.4-4, or Figure 18, abscissa -4 on Cor Ftn 4) is 0.3870; again the OI expected error is smaller.

As a general rule, expected error as calculated by OI will be optimistic when the observation errors are underestimated or when the spatial correlation is overestimated. The latter usually has a greater influence. On the other hand, when observation errors are overestimated or when the spatial correlation is underestimated, the expected error estimates computed by OI will be pessimistic. Any expected error estimates from operational OI sources should be treated with some caution, the examples above merely serving as an indication of the difficulties and not as a guide to the magnitude of the difference between the computed and actual values that may occur in practice.

#### 5.0 CONCLUDING REMARKS

The results of this study demonstrate that SI analyzed height errors are more sensitive to the decay rate for the spatial correlation function than for the additive constant. While this study concentrated on the SOAR correlation function, similar results can be expected for other correlation functions which are controlled by parameters governing similar properties. The wind errors are even more sensitive to proper values for the decay rate, unsurprising since the wind correction is related to the derivative of the spatial correlation function for the heights.

Another interesting observation is that it is better to "make the same mistake" relative to the observation error for the heights and winds. For example, if observed height error is specified as too large, smaller analysis errors occur when the observed wind errors are also specified as too large, rather than correct or too small. As a general rule, erring on the side of underestimating the observation error seems to result in smaller analysis errors than erring on the side of overestimation of the observation error.

The effect of one missing wind observation is vanishingly small. This is true even when one observation constitutes a significant portion of the total amount of data, as in the MA grid case. However, two things come into play in this case to make the missing data still rather insignificant: (1) the missing data is close to another observation, and (2) the skill in this case is rather low anyway. Missing much data (about

one-half) shows significant decreases in skill, about 20-25 percent for heights and up to 40 percent for the winds.

The relationship between the expected error that can be computed using SI and the actual values of the expected error were explored briefly. Practitioners need to be cognizant of the fact that these two values may be significantly different from each other.

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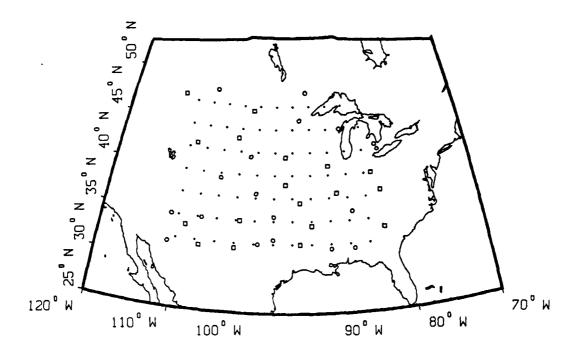


Figure 1: The Middle US (MUS) grid and observation locations. The +'s show the 2.5° grid. The open squares and circles and the shaded circle show observation locations. The shaded circle is a "missing observation" in one test run, and all circles are "missing observations" in another.

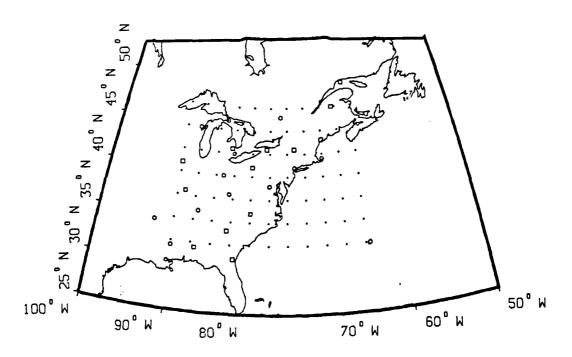


Figure 2: The East Coast (EC) grid and observation locations. Symbols as in Figure 1.

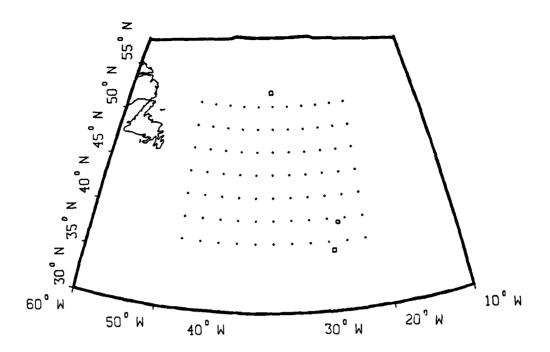


Figure 3: The Middle Atlantic (MA) grid and observation locations. Symbols as in Figure 1, except there is only a single "missing observation".

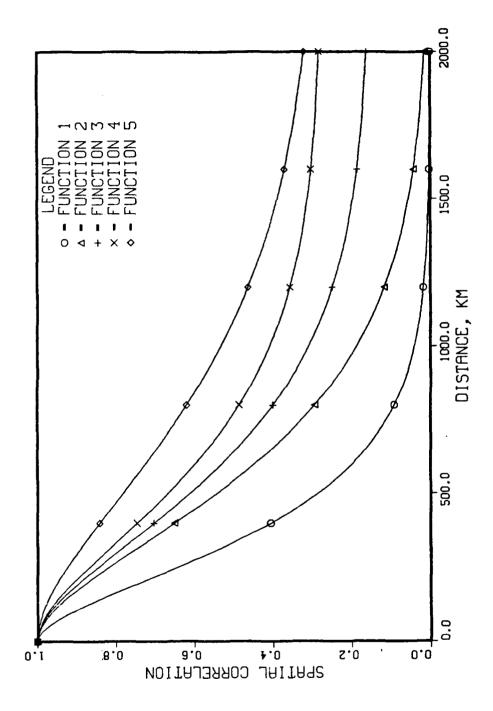


Figure 4: Spatial correlation functions.

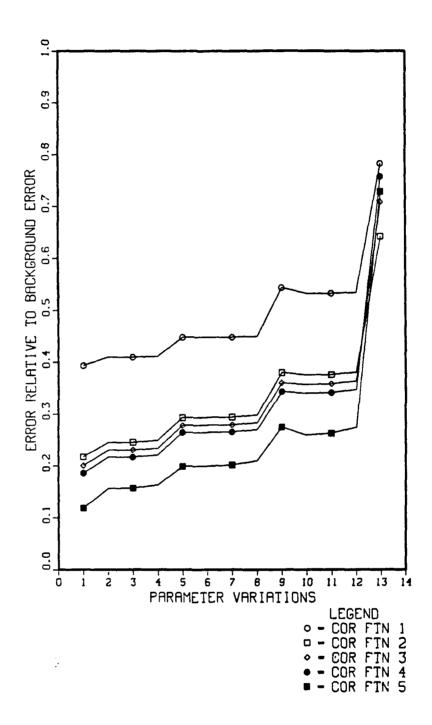


Figure 5: Expected error in OI height analysis under various observation error and spatial correlation function conditions for the MUS grid and observation set.

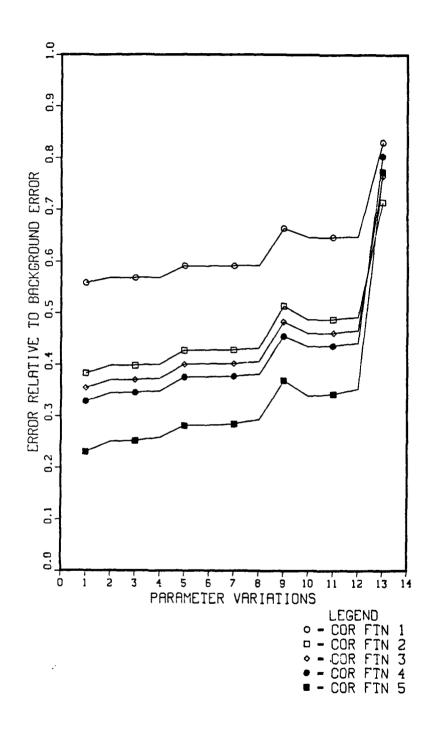


Figure 6: As in Figure 5, for the EC grid and observation set.

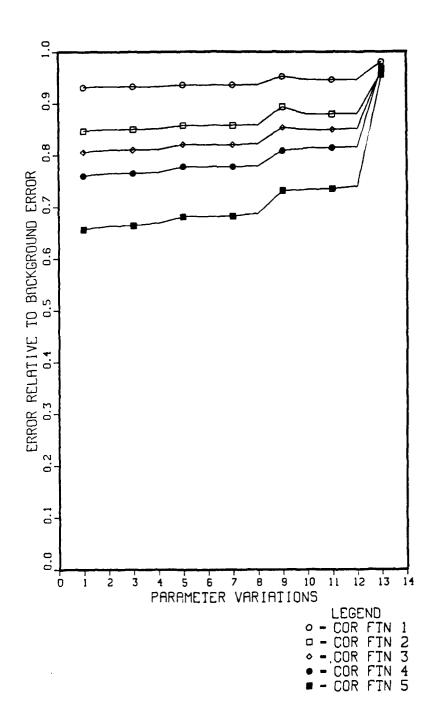


Figure 7: As in Figure 5, for the MA grid and observation set.

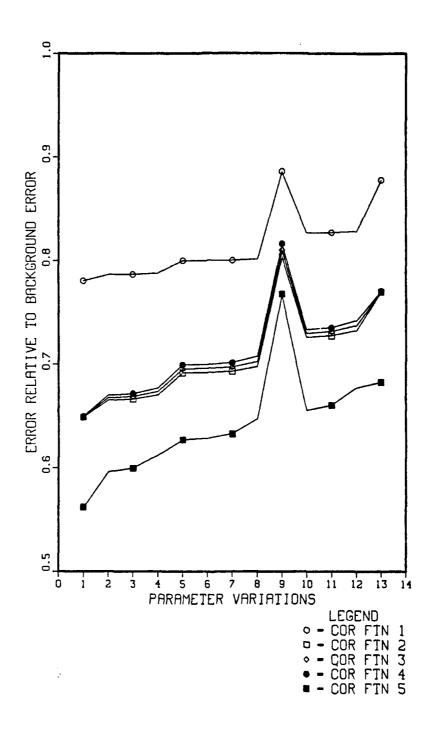


Figure 8: Expected error in OI wind analysis under various observation error and spatial correlation function conditions for the MUS grid and observation set.

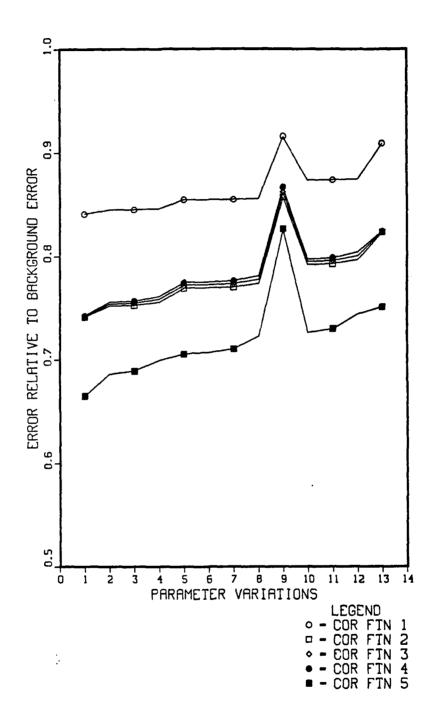


Figure 9: As in Figure 8, for the EC grid and observation set.

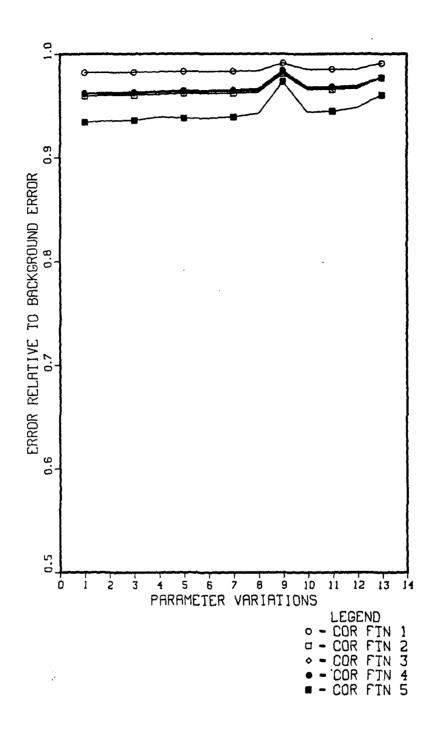


Figure 10: As in Figure 8, for the MA grid and observation set.

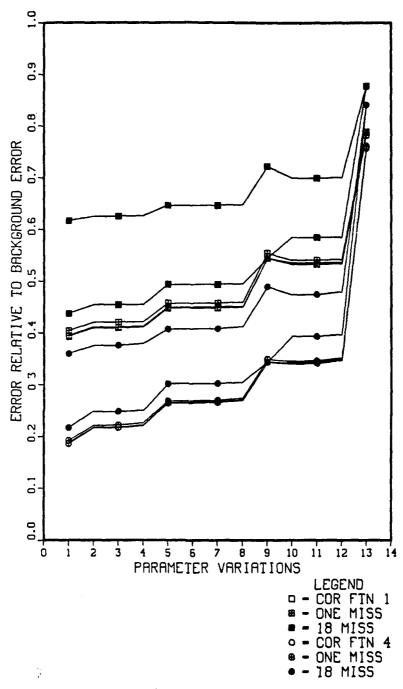


Figure 11: Expected error in OI height analysis under various observation error and spatial correlation function conditions for the MUS grid and observation set. The open square and circle mark the values for the entire observation set for correlation function numbers #1 and #4, respectively. The crossed square and circle mark two values; the lower for one missing wind observation, the upper one for both height and wind. The shaded square and circle mark two values; the lower one for 18 missing wind observations, the upper one for both heights and winds.

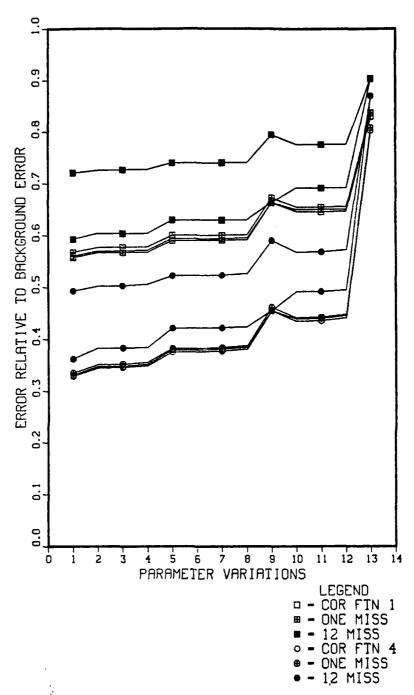


Figure 12: As in Figure 11, for EC grid and observation set, one and 12 missing observations.

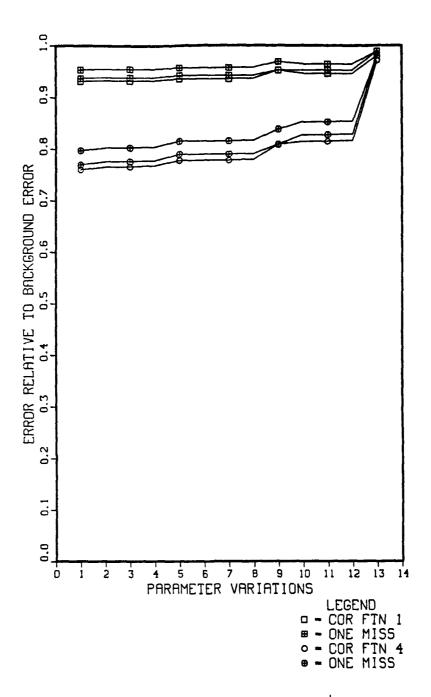


Figure 13: As in Figure 11, for MA grid and observation set, one missing observation (only).

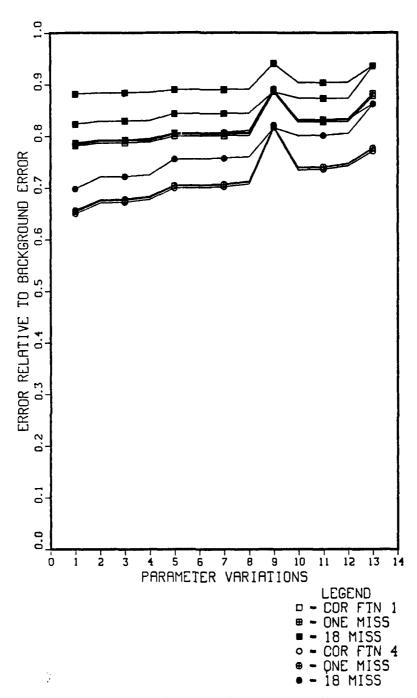


Figure 14: Expected error in OI wind analysis under various observation error and spatial correlation function conditions for the MUS grid and observation set. Symbols as in Figure 11.

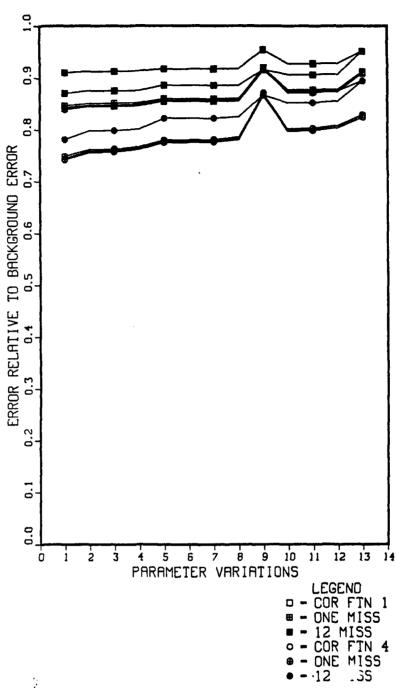


Figure 15: As in Figure 14, for EC grid and observation set, one and 12 missing observations.

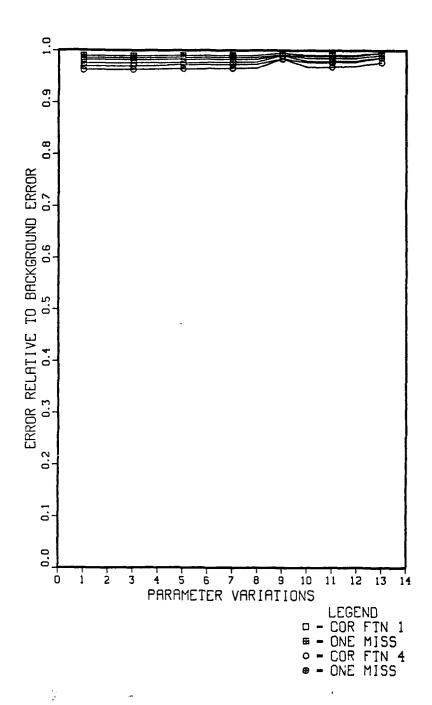


Figure 16: As in Figure 14, for MA grid and observation set, one missing observation (only).

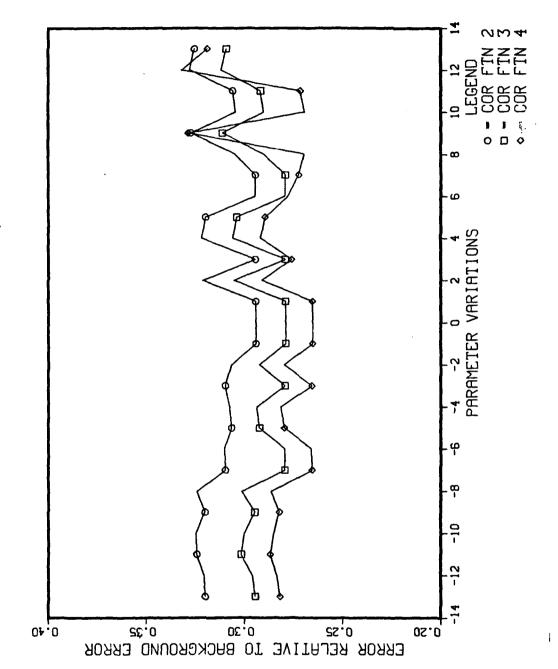


Figure 17: Expected error in the SI height analysis under various assumed correlation function and parameter values (see Table 4 for abscissae meanings), MUS grid and observation set.

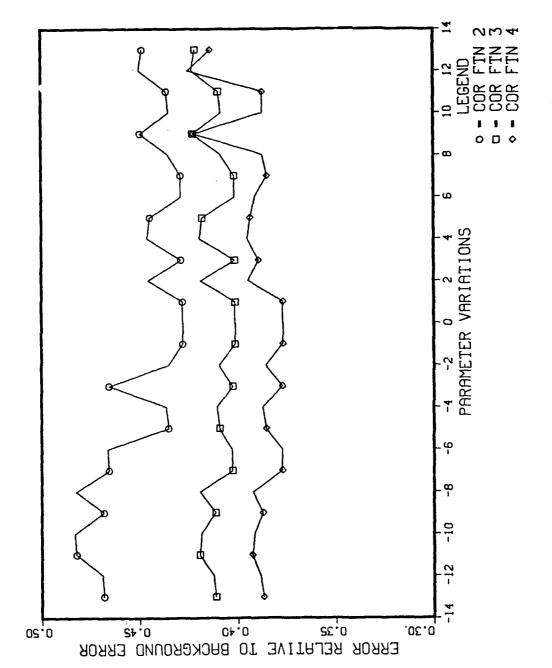
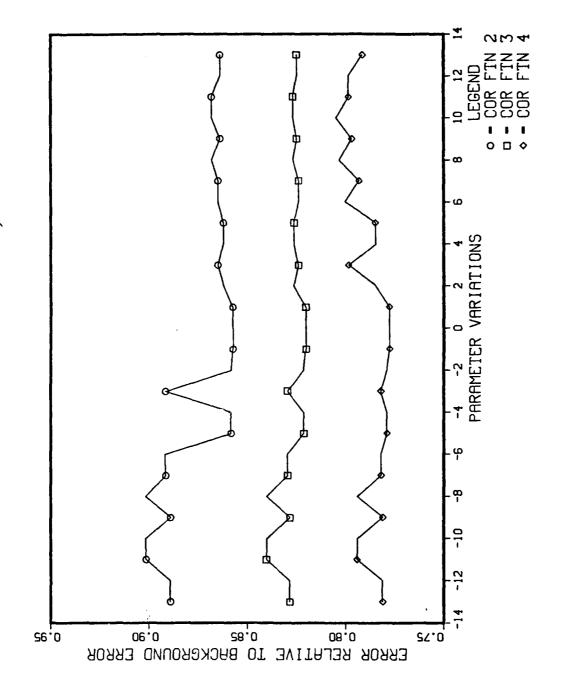


Figure 18: As in Figure 17 for the EC grid and observation set.



As in Figure 17 for the MA grid and observation set. Figure 19:

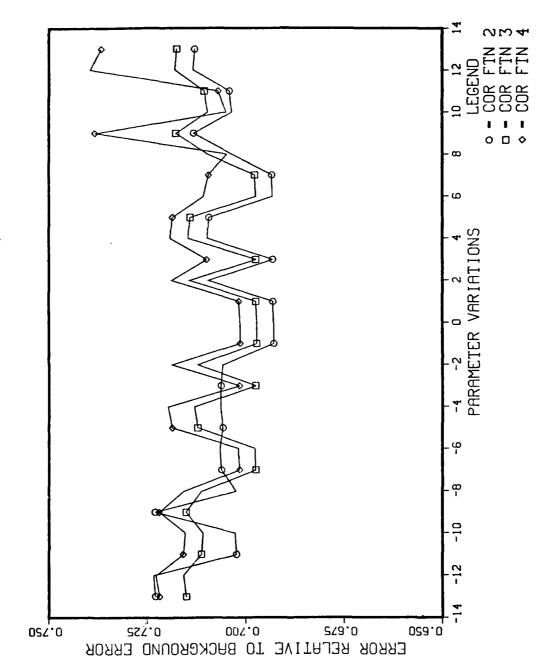
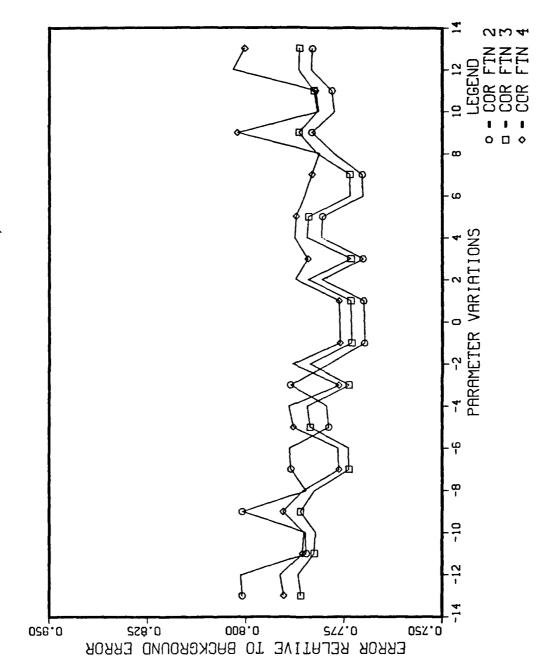


Figure 20: Expected error in the SI wind analysis under various assumed correlation function and parameter values (see Table 4 for abscissae meanings), MUS grid and observation set.



As in Figure 20 for the EC grid and observation set. Figure 21:

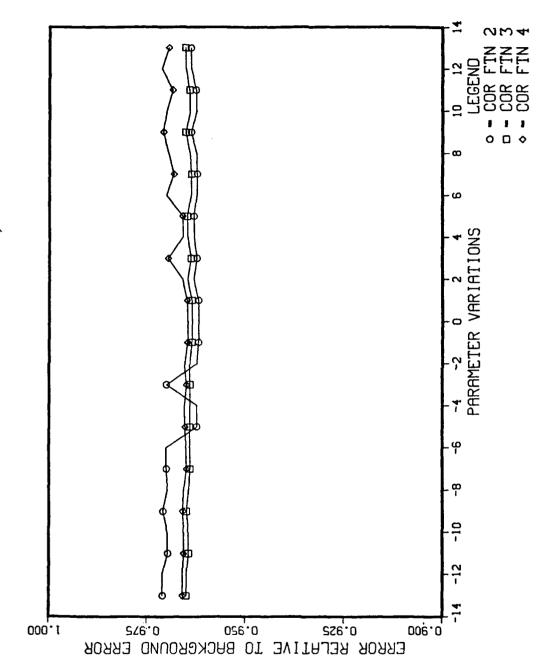


Figure 22: As in Figure 20 for the MA grid and observation set.

## APPENDIX 1: TABLES

The tables giving the values plotted in the various figures, and some additional data as well, are given here. Most of the information is more readily accessible in the figures, however the tables are given for completeness.

The numbering scheme for the tables is a key to the grid and observation set and the correlation function number used. The experiment whose results are given by the tables follows:

Table 1.g.m: Expected error under various values of parameters in OI, nominal observation data.

- q the grid used, 1 for MUS, 2 for EC, 3 for MA.
- m the spatial correlation function number, 1-5.

Table 2.g.m: Expected error under various values of parameters in OI, wind observation missing at one point, as noted in text and Figures 1-3. g and m as in Table 1.g.m, except m=1 or 4.

Table 3.g.m: Expected error under various values of parameters in OI, height and wind observation missing at one point, as noted in text and Figures 1-3. g and m as in Table 1.g.m, except m=1 or 4.

Table 4.g.m: Expected error under various values of parameters in OI, wind observations missing at about one-half the observation points, as noted in text and Figures 1-3. g and m as in Table 1.g.m, except m=1 or 4.

Table 5.g.m: Expected error under various values of parameters in OI, height and wind observations missing at about one-half the observation points, as noted in text and Figures 1-3. g and m as in Table 1.q.m, except m=1 or 4.

Table 6.g.m-n: Expected error under various values of parameters in SI.

- q the grid used, 1 for MUS, 2 for EC, 3 for MA.
- m the true spatial correlation function number, 1-5.
- n the assumed spatial correlation function number, 1-5, but not differing more than one from m.

Obs. error					
winds	0.0	5.0	rror, heiq	20.0	MoHeight
0.0			0.4474 0.8018 0.7978		
0.5		0.4090 0.7891 0.7834	0.4475 0.8019 0.7979	0.5321 0.8270 0.8263	
1.0	0.3927 0.7835 0.7771	0.4093 0.7893 0.7837	0.4478 0.8022 0.7982	0.5325 0.8273 0.8266	0.7828 0.8739 0.8814
2.0		0.4105 0.7905 0.7847	0.4491 0.8034 0.7992	0.5339 0.8285 0.8277	
MoWinds			0.5434 0.8911 0.8808		

Table 1.1.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	ints	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.2928		
ţ			0.6920		
1			0.6905		
0.5		0.2444	0.2931	0.3742	
1		0.6674	0.6924	0.7240	
i		0.6625	0.6908	0.7277	
1.0	0.2174	0.2452	0.2941	0.3754	0.6421
	0.6522	0.6645	0.6936	0.7253	0.7641
}	0.6454	0.6636	0.6920	0.7289	0.7752
2.0		0.2483	0.2975	0.3800	
		0.6728	0.6981	0.7303	
1		0.6677	0.6961	0.7336	
NoWinds			0.3794		
			0.8108		
J			0.7970		

Table 1.1.2: Expected error for observation accuracies

Obs. error		Obs. e	rror, held	hts	
vinds	0.0	5.0	10.0	20.0	WoHeight
0.0			0,2775		
1			0.6957		
			0.6947		
0.5		0.2291	0.2779	0.3560	
1		0.6697	0.6962	0.7275	
1		0.6651	0.6952	0.7318	
1.0	0.2007	0.2300	0.2789	0.3574	0.7078
	0.6525	0.6710	0.6976	0.7291	0.7645
į	0.6457	0.6664	0.6965	0.7333	0.7755
2.0		0.2333	0.2827	0.3624	•
,		0.6760	0.7029	0.7350	
i		0.6711	0.7014	0.7388	
MoWinds			0.3600		
			0.8169		
1			0.8032		

Table 1.1.3: Expected error for observation accuracies

Obs. error		Obs. e	rror, helq	hts	
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.2638		
			0.6994		
•			0.6989		
0.5		0.2157	0.2642	0.3391	
		0.6721	0.6999	0.7307	
1		0.6678	0.6994	0.7355	
1.0	0.1859	0.2166	0.2653	0.3406	0.7571
1	0.6529	0.6737	0.7016	0.7326	0.7649
	0.6460	0.6692	0.7010	0.7373	0.7759
2.0		0.2202	0.2694	0.3462	
		0.6794	0.7077	0.7395	
}		0.6746	0.7067	0.7437	
NoWinds			0.3427		
			0.8230		
1			0.8095		

Table 1.1.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
winds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.1983		
1			0.6255		
1			0.6283		
0.5		0.1549	0.1991	0.2591	
,		0.5969	0.6271	0.6516	
		0.5946	0.6297	0.6589	
1.0	0.1183	0.1567	0.2015	0.2625	0.7283
1	0.5653	0.6008	0.6315	0.6567	0.6772
İ	0.5583	0.5982	0.6338	0.6636	0.6879
2.0		0.1627	0.2095	0.2740	
1		0.6138	0.6462	0.6740	
		0.6101	0.6474	0.6798	
NoWinds			0.2743		
1			0.7753		
			0.7597		

Table 1.1.5: Expected error for observation accuracies

Obs. errori		Obs. e	rror, heig	hts	
winds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.5903 0.4543 0.8543		
0.5		0.5670 0.8435 0.8460	0.5904 0.8544 0.8544	0.6456 0.8747 0.8712	
1.0	0.5575 0.8386 0.8425	0.5672 0.8437 0.8462	0.5907 0.8546 0.8546	0.6459 0.8749 0.8714	0.8301 0.9119 0.9058
2.0		0.5681 0.8445 0.8470	0.5916 0.8554 0.8554	0.6471 0.8758 0.8723	
NoWinds			0.6631 0.9121 0.9190		

Table 1.2.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, beig	hts	
winds	0.0	5.0	10.0	20.0	NoMeight
0.0			0.4266		
i			0.7702		
l			0.7671		
0.5		0.3972	0.4269	0.4854	
- i		0.7515	0.7705	0.7939	
l		0.7516	0.7674	0.7886	
1.0	0.3828	0.3979	0.4277	0.4865	0.7146
5	0.7392	0.7523	0.7713	0.7949	0.8255
}	0.7426	0.7525	0.7683	0.7897	0.8202
2.0		0.4006	0.4310	0.4907	
1		0.7554	0.7746	0.7987	
1		0.7558	0.7718	0.7937	
Mowinds			0.5132		
			0.8544		
j			0.8593		

Table 1.2.2: Expected error for observation accuracies

Obs. error					
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.3998		
			0.7733 0.7 <b>699</b>		
0.5		0.3696	0.4001	0.4588	
		0.7537 0.7535	0.7737 0.7703	0.7969 0.7915	
1.0	0.3543	0.3703	0.4011	0.4600	0.7646
1	0.7399 0.7433	0.7546 0.7546	0.7747	0.7980 0.7928	0.8258 0.8205
2.0		0.3733	0.4046	0.4647	
ł		0.7582 0.7584	0.7786 0.7756	0.8025 0.7975	
NoWinds			0.4824		
			0.8595 0.8640		

Table 1.2.3: Expected error for observation accuracies

Obs. error			rror, beig		
vinda	0.0	5.0	10.0	20.0	MoReight
0.0			0.3753 0.7761		
ļ			0.7724		
0.5		0.3445	0.3756	0.4336	
· .		0.7556 0.7552	0.7765 0.7729	0.7994 0.7940	
1.0	0.3284	0.3454	0.3767	0.4350	0.8030
	0.7402 0.7437	0.7568 0.7564	0.7778 0.7742	0.8008 0.7955	0.8262
2.0		0.3486	0.3806	0.4402	
1		0.7609 0.7609	0.7823 0.7790	0. <b>0061</b> 0. <b>010</b>	
Nowinds			0.4544		
ļ .			0.8643 0.8684		

Table 1.2.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, helo	hts	
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.2 <b>811</b> 0.7072 0.7037		
0.5		0.2498 0.6865 0.6853	0.2819 0.7084 0.7050	0.3378 0.7277 0.7236	
1.0	0.2300 0.6627 0.6669	0.2517 0.6895 0.6884	0.2843 0.7118 0.7086	0.3410 0.7316 0.7277	0.7728 0.7524 0.7489
2.0		0.2580 0.6995 0.6990	0.2925 0.7234 0.7207	0.3519 0.7453 0.7417	
MoWinds			0.3686 0.8249 0.8274		

Table 1.2.5: Expected error for observation accuracies

Obs. error			rror, heig		
winda	0.0	5.0	10.0	20.0	NoHeight
0.0			0.9355		
			0.9817		
			0.9843		
0.5		0.9320	0.9355	0.9454	
Į.		0.9806	0.9817	0.9842	
[		0.9837	0.9843	0.9859	
1.0	0.9307	0.9321	0.9356	0.9455	0.9807
	0.9802	0.9806	0.9817	0.9842	0.9903
ì	0.9835	0.9837	0.9843	0.9860	0.9914
2.0		0.9323	0.9358	0.9457	
- 1		0.9808	0.9818	0.9843	
j		0.9838	0.9844	0.9861	
Nowinds			0.9520		
			0.9896		
			0.9922		

Table 1.3.1: Expected error for observation accuracies

Obs. error!	Obs. error, heights					
winds	0.0	5.0	10.0	20.0	NoHeight	
0.0			0.8567			
1			0.9585			
1			0.9649			
0.5		0.8491	0.8569	0.8783		
		0.9561	0.9585	0.9631		
[		0.9637	0.9649	0.9678		
1.0	0.6463	0.8494	0.8572	0.8787	0.9595	
	0.9550	0.9562	0.9587	0.9633	0.9752	
· · · · · · · · · · · · · · · · · ·	0.9634	0.9639	0.9651	0.9680	0.9788	
2.0		0.8508	0.8586	0.8801	•	
		0.9569	0.9594	0.9641		
1		0.9646	0.9658	0.9687		
MoWinds			0.8934			
			0.9767			
			0.9846			

Table 1.3.2: Expected error for observation accuracies

Obs. error		Obs. e	rror, helq	hts	
vinds	0.0	5.0	10.0	20.0	NoBeight
0.0			0.4196 0.9597		
0.5		0.8094 0.9572 0.9657	0.9668 0.8197 0.9598 0.9668	0.8486 0.9643 0.9694	
1.0	0.8058 0.9561 0.9655	0.8098 0.9574 0.9659	0.8201 0.9600 0.9670	0.8490 0.9645 0.9697	0.9657 0.9753 0.9788
2.0		0.8112 0.9582 0.9667	0.8216 0.9609 0.9678	0.8505 0.9654 0.9705	
Nowinds			0.8533 0.9783 0.9866		

Table 1.3.3: Expected error for observation accuracies

Obs. error					
winds	0.0	5.0	ror, heig	20.0	NoHeight
0.0			0.7769		
			0.9607		
}			0.9680		
0.5		0.7643	0.7770	0.8133	
1		0.9580	0.9608	0.9652	
,		0.9670	0.9681	0.9706	
1.0	0.7598	0.7647	0.7775	0.8137	0.9708
ì	0.9567	0.9583	0.9610	0.9655	0.9753
1	0.9667	0.9672	0.9683	0.9709	0.9789
2.0		0.7662	0.7790	0.8152	
-		0.9592	0.9620	0.9666	
		0.9681	0.9693	0.9718	
NoWinds			0.8084		
}			0.9795		
{			0.9880		

Table 1.3.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, beig	hts	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.6806		
• • • • • •			0.9293		
{			0.9457		
0.5		0.6626	0.6811	0.7332	
		0.9254	0.9296	0.9373	
1		0.9444	0.9460	0.9497	
1.0	0.6565	0.6639	0.6824	0.7345	0.9552
	0.9233	0.9263	0.9306	0.9383	0.9573
	0.9444	0.9452	0.9468	0.9506	0.9632
2.0		0.6684	0.6870	0.7349	
		0.9294	0.9341	0.9420	
1		0.9482	0.9499	0.9537	
MoWinds			0.7311		
			0.9642		
1			0.9818		

Table 1.3.5: Expected error for observation accuracies

Obs. error	Obs. error, heights					
vinds	0.0	5.0	10.0	20.0	NoBelght	
0.0			0.4493			
1			0.8064			
J			0.8005			
0.5		0.4107	0.4494	0.5345		
}		0.7935	0.8065	0.8317		
1		0.7861	0.8006	0.8290		
1.0	0.3944	0.4110	0.4497	0.5349	0.7879	
- {	0.7879	0.7938	0.8067	0.8320	0.8794	
	0.7798	0.7864	0.8008	0.8293	0.8844	
2.0		0.4123	0.4510	0.5363		
į		0.7949	0.8078	0.8331		
1		0.7874	0.8019	0.8303		
NoWinds			0.5434			
			0.8911			
}			0.8808			

Table 2.1.1: Expected error for observation accuracies

Obs. error!					
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.2652		
l			0.7040		
1			0.7018		
0.5		0.2167	0.2656	0.3414	
ľ		0.6764	0.7045	0.7359	
j		0.6706	0.7023	0.7386	
1.0	0.1868	0.2177	0.2667	0.3429	0.7604
1	0.6570	0.6779	0.7061	0.7377	0.7711
}	0.6487	0.6720	0.7038	0.7403	0.7797
2.0		0.2212	0.2708	0.3484	
í		0.6834	0.7120	0.7444	
i		0.6772	0.7094	0.7467	
NoWinds			0.3427		
1			0.6230		
3			0.4095		

Table 2.1.4: Expected error for observation accuracies

Obs. error					
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.5937		
1			0.8556		
į.			0.8571		
0.5		0.5702	0.5938	0.6497	
ł		0.8448	0.8557	0.4761	
}		0.8487	0.8571	0.2742	
1.0	0.5606	0.5704	0.5941	0.6500	0.8372
	0.4399	0.8450	0.8559	0.8763	0.9136
· .	0.4451	0.8489	0.8574	0.4745	0.9096
2.0		0.5713	0.5950	0.6511	
		0.6456	0.4567	0.8771	
1		0.8497	0.6542	0.8753	
MoWinds			0.6631		
· · · · · · · · · · · · · · · · · · ·			0.9121		
			0.9190		

Table 2.2.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.3788		
			0.7781		
ļ ļ			0.7762		
0.5		0.3474	0.3792	0.4384	
		0.7574	0.7785	0.8019	
		0.7585	0.7766	0.7984	
1.0	0.3308	0.3482	0.3802	0.4397	0.8087
i i	0.7419	0.7585	0.7797	0.8033	0.8297
	0.7467	0.7596	0.7779	0.7998	0.8264
2.0		0,3513	0.3840	0.4448	
		0.7626	0.7842	0.8085	
		0.7640	0.7826	0.8052	
NoWinds			0.4544		
			0.8643		
1			0.8684		

Table 2.2.4: Expected error for observation accuracies

Obs. errori					
winds	0.0	5.0	rror, heig	20.0	NoHeight
0.0			0.9420		
			0.9864		
i			0.9870		
0.5		0.9382	0.9421	0.9525	
l l		0.9654	0.9865	0.9891	
}		0.9863	0.9870	0.9888	
1.0	0.9368	0.9383	0.9421	0.9525	0.9885
	0.9850	0.9854	0.9865	0.9891	0.9957
ì	0.9861	0.9863	0.9870	0.9888	0.9945
2.0		0.9384	0.9423	0.9527	
· · · · · )		0.9854	0.9865	0.9891	
l l		0.9864	0.9871	0.9889	
Nowinds			0.9520		
			0.9896		
j			0.9922		

Table 2.3.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.8143		
			0.9752		
0.5		0.8014	0.8144	0.6515	
}		0.9741 0.9765	0.9753 0.9773	0.9783 0.9795	
.1.0	0.7968	0.8017	0.8148	0.8518	0.9805
	0.9738 0.9764	0.9743 0.9767	0.9754 0.9775	0.9785 0.9797	0.9869
2.0		0.8029	0.8160	0.8530	
		0.9749	0.9761	0.9792 0.9804	
MoWinds			0.8378		
			0.9887 0.9914		

Table 2.3.4: Expected error for observation accuracies

Obe. error		Obs. e	gror, heig	hts	
vinds	0.0	5.0	10.0	20.0	NoBeight
0.0			0.4570		
1			0.8043		
0.5		0.4198	0.4571	0.5400	
(		0.7941 0.7904	0.8066 0.8044	0.8310 0.8320	
1.0	0.4042	0.4202	0.4574	0.5404	0.7892
ļ	0.7888	0.7 <b>944</b> 0.7 <del>906</del>	0.8069	0.4312	0.8772 0.8864
2.0		0.4214	0.4587	0.5418	
		0.7955 0.7917	0.8080 0.8057	0.8324	
Mowinds			0.5534		
1			0.8946		

Table 3.1.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig		
winds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.2681		
			0.7038		
1			0.7047		
0.5		0.2207	0.2685	0.3439	
***		0.6771	0.7043	0.7348	
j		0.6744	0.7052	0.7411	
1.0	0.1919	0.2217	0.2697	0.3454	0.7616
*.0	0.6585	0.6787	0.7059	0.7366	0.7698
1	0.6533	0.6758	0.7067	0.7428	0.7819
2.0		0.2253	0.2738	0.3509	
		0.6844	0.7120	0.7435	
(		0.6811	0.7123	0.7490	
NoWinds			0.3482		
			0.8266		
			0.8133		

Table 3.1.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, beig	hts	
winds	0.0	5.0	10.0	20.0	HoHeight
0.0			0.6000		
			0.8595		
i			0.8592		
0.5		0.5771	0.6001	0.6544	
		0.8496	0.8596	0.8784	
1		0.8512	0.8593	0.8756	
1.0	0.5674	0.5773	0.6003	0.6547	0.8372
	0.8452	0.8498	0.8598	0.8786	0.9138
1	0.8478	0.8514	0.8595	0.8758	0.9096
7.0		0.5782	0.6013	0.6558	•
7.0		0.8506	0.8606	0.8794	
		0.8522	0.8603	0.8767	
MoWinds			0.6723		
			0.9166		
			0.9221		

Table 3.2.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
vinds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.3816		
1			0.7805		
			0.7778		
0.5		0.3509	0.3820	0.4406	
i		0.7614	0.7809	0.8029	
		0.7609	0.7782	0.7991	
1.0	0.3348	0.3518	0.3831	0.4420	0.8087
	0.7474	0.7625	0.7821	0.8043	0.8297
1	0.7498	0.7621	0.7795	0.8006	0.8264
2.0		0.3550	0.3870	0.4472	
		0.7667	0.7867	0.8096	
1		0.7665	0.7843	0.8060	
Mowinds			0.4611		
			0.8689		
ł			0.8721		

Table 3.2.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, held	hts	
vinds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.9569		
1			0.9902		
Į.			0.9896		
0.5		0.9543	0.9569	0.9643	
1		0.9897	0.9902	0.9914	
		0.9892	0.9896	0.9908	
1.0	0.9534	0.9544	0.9570	0.9643	0.9885
1	0.9896	0.9897	0.9902	0.9915	0.9957
	0.9891	0.9893	0.9896	0.9908	0.9945
2.0		0.9545	0,9572	0.9645	
		0.9898	0.9902	0.9915	
		0.9893	0.9897	0.9909	
MoWinds			0.9688		
			0.9945		
i			0.9951		

Table 3.3.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, beig	hts	
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.7889		
1			0.9695		
j			0.9747		
0.5		0.7747	0.7890	0.8264	
Ť		0.9659	0.9695	0.9755	
}		0.9732	0.9747	0.9777	
1.0	0.7691	0.7750	0.7893	0.8267	0.9805
	0.9642	0.9661	0.9697	0.9757	0.9869
· .	0.9727	0.9734	0.9749	0.9779	0.9862
2.0		0.7761	0.7903	0.8277	
		0.9666	0.9702	0.9762	
į		0.9741	0.9756	0.9786	
MoWinds			0.8084		
			0.9795		
Į.			0.9880		

Table 3.3.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, beig	hts	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.4933		
			0.8457 0.8406		
0.5		0.4540	0.4933	0.5838	
		0.8321 0.8253	0.8457 0.8407	0.8734 0.8720	
1.0	0.4377	0.4542	0.4935	0.5840	0.8774
· i	0.8262 0.8187	0.8322 0.8255	0.8459 0.8408	0.8735 0.8721	0.9305 0.9399
2.0		0.4548	0.4942	0.5848	
ļ		0.8328 0.8260	0.8465 0.8413	0.8741 0.8727	
NoWinds			0.5434		
ļ			0.8911		

Table 4.1.1: Expected error for observation accuracies

Obs. error			rror, heig		
vinds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.3014		
			0.7570		
			0.7534		
0.5		0.2477	0.3016	0.3920	
		0.7244	0.7573	0.7983	
ţ		0.7167	0.7537	0.8016	
1.0	0.2167	0.2482	0.3022	0.3929	0.8412
	0.7026	0.7253	0.7583	0.7994	0.8541
ĺ	0.6924	0.7175	0.7545	0.8025	0.8688
2.0		0.2500	0.3045	0.3962	
· · )		0.7285	0.7617	0.8035	
į		0.7202	0.7574	0.8060	
MoWinds			0.3427		
			0.8230		
1			0.8095		

Table 4.1.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hte	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.6297		
1			0.8847		
			0.8860		
0.5		0.6038	0.6297	0.6915	
ļ		0.8731	0.8847	0.9076	
		0.8768	0.8860	0.9053	
1.0	0.5932	0.6039	0.6298	0.6916	0.9039
	0.8679	0.8732	0.8848	0.9077	0.9537
	0.8729	0.8769	0.8862	0.9054	0.9481
2.0		0.6043	0.6303	0.6922	•
7		0.8735	0.8852	0.9081	
1		0.8774	0.8866	0.9059	
MoWinds			0.6632		
1			0.9121		
1			0.9190		

Table 4.2.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.4211		
-			0.8237		
			0.8191		
0.5		0.3826	0.4212	0.4911	
· · · · · · · · · · · · · · · · · · ·		0.7977	0.8239	0.8555	
į.		0.7970	0.8193	0.8483	
1.0	0.3617	0.3830	0.4217	0.4918	0.8703
	0.7796	0.7982	0.8245	0.8562	0.8978
	0.7826	0.7976	0.8200	0.8491	0.8897
2.0		0.3843	0.4234	0.4945	
		0.8003	0.8268	0.8590	
		0.7999	0.8226	0.8522	
NoWinds			0.4544		
****			0.8643		
1			0.8684		

Table 4.2.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
vinds	0.0	5.0	10.0	20.0	MoMeight
0.0			0.6457 0.8893		
}			0.8900		
0.5		0.6247 0.8831 0.8838	0.6458 0.8894 0.8901	0.6989 0.9024 0.9042	
1.0	0.6166 0.8806 0.8814	0.6250 0.8833 0.8840	0.6461 0.8895 0.8902	0.6991 0.9026 0.9043	0.8774 0.9305 0.9399
2.0		0.6258 0.8839 0.8845	0.6470 0.8902 0.8908	0.7001 0.9033 0.9049	
NoWinds			0.7214 0.9415 0.9390		

Table 5.1.1: Expected error for observation accuracies

Obs. error!		Obs. e	rror, heig	hts	
winds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.4067		
			0.8070		
İ			0.8035		
0.5		0.3747	0.4070	0.4729	
- 1		0.7926	0.8074	0.8263	
1		0.7875	0.8039	0.8289	
1.0	0.3595	0.3756	0.4080	0.4741	0.8412
	0.7838	0.7936	0.8085	0.8275	0.8541
ĺ	0.7769	0.7885	0.8049	0.8300	0.8688
2.0		0.3789	0.4118	0.4787	
}		0.7975	0.8126	0.8322	
		0.7920	0.8085	0.8340	
NoWinds			0.4887		
			0.8949		
ľ			0.8862		

Table 5.1.4: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hta	
vinds	0.0	5.0	10.0	20.0	NoHeight
0.0			0.7397		
			0.9175		
1			0.9164		
0.5		0.7260	0.7398	0.7753	
1		0.9123	0.9175	0.9286	
		0.9121	0.9164	0.9260	
1.0	0.7207	0.7262	0.7400	0.7755	0.9039
ĺ	0.9103	0.9125	0.9177	0.9287	0.9537
ı	0.9103	0.9122	0.9166	0.9261	0.9481
2.0		0.7268	0.7406	0.7762	•
		0.9129	0.9181	0.9292	
[		0.9127	0.9171	0.9266	
Mowinds			0.7946		
1			0.9523		
}			0.9554		

Table 5.2.1: Expected error for observation accuracies

Obs. error		Obs. e	rror, heig	hts	
vinds	0.0	5.0	10.0	20.0	MoHeight
0.0			0.5221		
ļ			0.8580		
0.5		0.5022	0.5224	0.5674	
İ		0.8465 0.8440	0.8582	0.8738 0.8682	
1.0	0.4931	0.5028	0.5232	0.5684	0.8703
	0.8396 0.8382	0.8472 0.8448	0.8590 0.8552	0. <b>8746</b> 0. <b>869</b> 1	0.8978 0.8897
2.0		0.5054	0.5262	0.5722	
ļ		0.8498 0.8477	0.8618 0.8583	0.8779 0.8727	
MoWinds			0.5899		
ı			0.9181 0.9214		

Table 5.2.4: Expected error for observation accuracies

Assmd Obs.	Assumed 5.0	Obs. error, 10.0	beights 20.0
0.5	0.4531	0.4478	0.4717
	0.8052	0.8022	0.8118
	0.8015	0.7982	0.8087
1.0	0.4531	0.4478	0.4716
·	0.6052	0.6022	0.4117
	0.8015	0.7982	0.8087
2.0	0.4532	0.4478	0.4713
	0.8052	0.8022	0.8117
	0.8015	0.7982	0.8087

Table 6.1.1-1: Variation of expected error

Assad Obs.	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.4583	0.4709	0.5476
1	0.8064	0.8120	0.8379
1	0.8020	0.8081	0.8371
1.0	0.4580	0.4699	0.5457
1	0.8061	0.8116	0.8374
	0.8017	0.8077	0.8366
2.0	0.4568	0.4666	0.5387
	0.8054	0.8105	0.8356
	0.8011	0.8067	0.8349

Table 6.1.1-2: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.3200	0.3096	0.3242
	0.7226	0.7068	0.7032
}	0.7232	0.7054	0.7014
1.0	0.3201	0.3097	0.3243
1	0.7227	0.7069	0.7033
	0.7233	0.7055	0.7015
2.0	0.3205	0.3101	0.3247
	0.7230	0.7073	0.7036
	0.7235	0.7058	0.7018

Table 6.1.2-1: Variation of expected error

Assed Obs.		Obs. error,	
err, winds	5.0	10.0	20.0
0.5	0.3064	0.2941	0.3217
	0.7060	0.6936	0.7094
ļ	0.7054	0.6920	0.7100
1.0	0.3066	0.2941	0.3212
	0.7060	0.6936	0.7093
	0.7055	0.6920	0.7099
2.0	0.3076	0.2942	0.3197
	0.7066	0.6938	0.7090
	0.7060	0.6921	0.7096

Table 6.1.2-2: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	beights 20.0
0.5	0.3045	0.2945	0.3279
	0.7038	0.6939	0.7127
	0.7030	0.6923	0.7139
1.0	0.3047	0.2944	0.3273
j	0.7039	0.6939	0.7126
	0.7031	0.6922	0.7137
2.0	0.3059	0.2944	0.3255
	0.7045	0.6941	0.7123
	0.7037	0.6924	0.7134

Table 6.1.2-3: Variation of expected error

asmd Obs. err, winds	5.0	Obs. error,	heights 20.0
0.5	0.2945	0.2793	0.3016
}	0.7149	0.6980	0.7108
ļ	0.7152	0.6968	0.7116
1.0	0.2947	0.2793	0.3012
	0.7150	0.6980	0.7107
ſ	0.7153	0.6968	0.7115
2.0	0.2958	0.2796	0.2999
	0.7156	0.6982	0.7104
Į.	0.7159	0.6971	0.7112

Table 6.1.3-2: Variation of expected error

Assad Obs. err, winds	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.2922	0.2789	0.3059
1	0.7121	0.6977	0.7139
	0.7122	0.6965	0.7152
1.0	0.2925	0.2789	0.3054
	0.7122	0.6976	0.7137
i	0.7123	0.6965	0.7150
2.0	0.2937	0.2791	0.3038
	0.7129	0.6979	0.7134
	0.7130	0.6967	0.7147

Table 6.1.3-3: Variation of expected error

err, vinds	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.2901	0.2793	0.3118
	0.7096	0.6979	0.7170
į	0.7095	0.6968	0.7188
1.0	0.2904	0.2792	0.3112
	0.7097	0.6979	0.7168
i	0.7096	0.6968	0.7186
2.0	0.2918	0.2792	0.3092
	0.7106	0.6982	0.7165
1	0.7104	0.6970	0.7183

Table 6.1.3-4: Variation of expected error

assed Obs. err, winds		Obs. error, 10.0	heights 20.0
0.5	0.2819	0.2655	0.2868
	0.7213 0.7224	0.7018 0.7013	0.7151 0.7166
1.0	0.2822	0.2656 0.7018	0.2864
	0.7225	0.7012	0.7164
2.0	0.2835	0.2659	0.2850
	0.7222 0.7232	0.7021 0.7015	0.7147 0.7161

Table 6.1.4-3: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.2796	0.2653	0.2917
	0.7182	0.7016	0.7181
ļ	0.7190	0.7010	0.7200
1.0	0.2799	0.2653	0.2912
	0.7184	0.7016	0.7179
	0.7192	0.7010	0.7198
2.0	0.2814	0.2655	0.2894
	0.7193	0.7019	0.7176
	0.7201	0.7013	0.7195

Table 6.1.4-4: Variation of expected error

Assmd Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.2693	0.2777	0.3320
į.	0.7051	0.7105	0.7369
1	0.7046	0.7107	0.7420
1.0	0.2695	0.2760	0.3287
i i	0.7050	0.7097	0.7358
	0.7046	0.7100	0.7408
2.0	0.2716	0.2724	0.3190
	0.7072	0.7092	0.7341
	0.7067	0.7095	0.7391

Table 6.1.4-5: Variation of expected error

Assmd Obs.	<b>Dogunas</b>	Obs. error,	heights
err, vinds	5.0	10.0	20.0
0.5	0.2383	0.2095	0.2117
	0.7005	0.6431	0.6370
1	0.7084	0.6465	0.6398
1.0	0.2388	0.2099	0.2117
	0.7009	0.6434	0.6371
	0.7088	0.6468	0.6399
2.0	0.2408	0.2113	0.2120
1	0.7029	0.6448	0.6377
1	0.7106	0.6481	0.6404

Table 6.1.5-4: Variation of expected error

Assud Obs. err, vinds	Assumed 5.0	Obs. error, 10.0	heighta 20.0
0.5	0.2187	0.2016	0.2237
1	0.6587	0.6316	0.6467
1	0.6640	0.6339	0.6517
1.0	0.2198	0.2015	0.2224
	0.6595	0.6315	0.6461
	0.6647	0.6338	0.6511
2.0	0.2242	0.2024	0.2192
	0.6645	0.6331	0.6462
ſ	0.6694	0.6354	0.6511

Table 6.1.5-5: Variation of expected error

err, winds	Assumed 6	obs. error, 10.0	heights 20.0
0.5	0.5939	0.5907	0.6057
i	0.8574	0.8546	0.4626
1	0.8564	0.8546	0.8608
1.0	0.5940	0.5907	0.6056
	0.8574	0.8546	0.8626
1	0.8564	0.8546	0.8607
2.0	0.5941	0.5907	0.6054
	0.4574	0.8546	0.8636
i	0.8565	0.4546	0.8607

Table 6.2.1-1: Variation of expected error

Assmd Obs.	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.6311	0.6368	0.6817
	0.8631	0.8681	0.8884
	0.8627	0.8663	0.8832
1.0	0.6304	0.6356	0.6797
	0.8628	0.8677	0.8879
	0.8625	0.8659	0.8827
2.0	0.6279	0.6313	0.6725
	0.8620	0.8665	0.8863
í	0.8617	0.8647	0.8810

Table 6.2.1-2: Variation of expected error

Assed Obs. err, winds	Assumed 0	10.0	beighte 20.0
0.5	0.4682	0.4655	0.4823
	0.8059	0.7913	0.7865
į	0.7957	0.7857	0.7826
1.0	0.4683	0.4656	0.4824
	0.8060	0.7913	0.7865
	0.7957	0.7858	0.7826
2.0	0.4649	0.4661	0.4830
	0.8063	0.7916	0.7868
ſ	0.7961	0.7861	0.7829

Table 6.2.2-1: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.4351	0.4278	0.4458
	0.7818	0.7713	0.7830
	0.7759	0.7683	0.7785
1.0	0.4353	0.4277	0.4455
	0.7818	0.7713	0.7829
	0.7760	0.7683	0.7784
2.0	0.4362	0.4279	0.4445
	0.7823	0.7715	0.7827
	0.7765	0.7685	0.7782

Table 6.2.2-2: Variation of expected error

Assad Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.4348	0.4287	0.4499
	0.7800	0.7717	0.7856
	0.7748	0.7687	0.7809
1.0	0.4350	0.4287	0.4495
	0.7801	0.7717	0.7855
	0.7749	0.7687	0.7808
2.0	0.4360	0.4287	0.4483
	0.7807	0.7719	0.7853
1	0.7754	0.7689	0.7806

Table 6.2.2-3: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	
0.5	0.4111	0.4025	0.4193
í	0.7895	0.7753	0.7848
	0.7824	0.7720	0.7803
1.0	0.4113	0.4025	0 11
j	0.7896	0.7753	C 47
[	0.7825	0.7720	002
2.0	0.4123	0.4028	0.4183
	0.7902	0.7755	0.7845
1	0.7830	0.7722	0.7800

Table 6.2.3-2: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.4091	0.4011	0.4192
	0.7868	0.7747	0.7867
1	0.7803	0.7714	0.7820
1.0	0.4093	0.4011	0.4188
	0.7869	0.7747	0.7866
1	0.7804	0.7714	0.7818
2.0	0.4104	0.4012	0.4178
	0.7875	0.7749	0.7863
1	0.7810	0.7716	0.7816

Table 6.2.3-3: Variation of expected error

Assud Obs. err, vinds	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.4081	0.4015	0.4230
	0.7846	0.7750	0.7890
1	0.7788	0.7717	0.7841
1.0	0.4084	0.4014	0.4226
	0.7847	0.7749	0.7889
}	0.7789	0.7716	0.7840
2.0	0.4096	0.4015	0.4213
	0.7855	0.7752	0.7886
Í	0.7797	0.7719	0.7838

Table 6.2.3-4: Variation of expected error

Assmd Obs.	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.3868	0.3771	0.3924
0.5	0.7942	0.3771	0.7879
	0.7864	0.7780	0.7832
-	U. /804	0.7745	0.7632
1.0	0.3871	0.3771	0.3921
	0.7943	0.7780	0.7877
	0.7866	0.7744	0.7830
2.0	0.3883	0.3774	0.3912
ĺ	0.7951	0.7783	0.7875
	0.7873	0.7747	0.7828

Table 6.2.4-3: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.3854	0.3767	0.3948
	0.7 <b>914</b> 0.7 <b>844</b>	0.7778 0.7742	0.7899 0.7851
1.0	0.3857	0.3767	0.3944
	0.7916 0.7846	0.7778 0.7742	0.7898
2.0	0.3870	0.3769	0.3933
	0.7925 0.7854	0.7780 0.7745	0.7896

Table 6.2.4-4: Variation of expected error

Assmd Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heighte 20.0
0.5	0.3872	0.3908	0.4253
1	0.7834	0.7872	0.8060
	0.7795	0.7828	0.8003
1.0	0.3869	0.3891	0.4223
i	0.7831	0.7864	0.8049
	0.7793	0.7820	0.7993
2.0	0.3872	0.3849	0.4137
_ · · ·	0.7841	0.7852	0.8029
	0.7803	0.7811	0.7975

Table 6.2.4-5: Variation of expected error

Assud Obs. err, winds	Assumed 5.0	Obs. error,	heighta 20.0
0.5	0.3106		0.3036
	0.7703 0.7 <b>549</b>		0.7203 0.7167
1.0	0.3112	0.2950	0.3038
	0.7553	0.7199	0.7168
2.0	0.3136	0.2967 0.7258	0.3049
	0.7729	0.7213	0.7176

Table 6.2.5-4: Variation of expected error

Assud Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.2952	0.2844	0.3019
	0.7322 0.7253	0.7119 0.7087	0.7231 0.7192
1.0	0.2961	0.2843 0.7118	0.3009
	0.7260	0.7086	0.7188
2.0	0.3001	0.2852 0.7132	0.2990
	0.7300	0.7100	0.7190

Table 6.2.5-5: Variation of expected error

Assmd Obs.	Assumed 5.0	Obs. error,	
0.5	0.9359	0.9356	0.9379
ŀ	0.9819	0.9817	0.9825
ļ	0.9844	0.9843	0.9847
1.0	0.9359	0.9356	0.9379
	0.9819	0.9817	0.9825
i	0.9844	0.9843	0.9847
2.0	0.9359	0.9356	0.9379
· .	0.9819	0.9817	0.9825
1	0.9844	0.9843	0.9847

Table 6.3.1-1: Variation of expected error

Assed Obs.		Obs. error,	
err, winds	5.0	10.0	20.0
0.5	0.9916	0.9873	0.9807
1	0.9878	0.9879	0.9897
	0.9901	0.9902	0.9908
1.0	0.9907	0.9863	0.9796
	0.9876	0.9878	0.9895
	0.9899	0.9900	0.9907
2.0	0.9872	0.9826	0.9757
	0.9871	0.9872	0.9889
1	0.9894	0.9895	0.9901

Table 6.3.1-2: Variation of expected error

Assmd Obs. err, winds	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.8889	0.8913	0.9013
1	0.9678	0.9669	0.9670
	0.9740	0.9732	0.9723
1.0	0.8890	0.8914	0.9014
1	0.9678	0.9669	0.9671
	0.9740	0.9732	0.9724
2.0	0.8892	0.4916	0.9016
	0.9679	0.9670	0.9672
i	0.9741	0.9733	0.9724

Table 6.3.2-1: Variation of expected error

Assed Obs.	Assumed	Obs. error,	heighte
err, winds	5.0	10.0	20.0
0.5	0.8581	0.8572	0.8620
1	0.9595	0.9587	0.9603
	0.9653	0.9651	0.9658
1.0	0.8581	0.8572	0.8619
1	0.9595	0.9587	0.9603
	0.9653	0.9651	0.9658
2.0	0.8583	0.8573	0.8620
į.	0.9596	0.9587	0.9603
	0.9653	0.9651	0.9658

Table 6.3.2-2: Variation of expected error

Assad Obs. err, winds	Assumed 6	10.0	heights 20.0
0.5	0.8680	0.8649	0.8639
i	0.9595	0.9590	0.9611
	0.9656	0.9656	0.9667
1.0	0.8680	0.8649	0.8638
i	0.9595	0.9590	0.9611
1	0.9656	0.9656	0.9667
2.0	0.8681	0.8649	0.8639
	0.9596	0.9590	0.9611
	0.9657	0.9656	0.9668

Table 6.3.2-3: Variation of expected error

		Obs. error,	
err, winds	5.0	10.0	20.0
0.5	0.8284	0.8294	0.8402
	0.9616	0.9604	0.9613
1	0.9683	0.9677	0.9675
1.0	0.8284	0.8294	0.8402
-11	0.9616	0.9604	0.9613
	0.9683	0.9677	0.9675
2.0	0.8286	0.8295	0.8402
ł	0.9617	0.9604	0.9613
i i	0.9683	0.9677	0.9676

Table 6.3.3-2: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heighta 20.0
0.5	0.8212	0.8201	0.8261
	0.9610		0.9617
	0.9673	0.9671	0.9677
1.0	0.8212	0.8201	0.8261
	0.9610		0.9617
·	0.9673	0.9670	0.9677
2.0	0.8213	0.8202	0.8261
	0.9611	0.9601	0.9617
	0.9673	0.9671	0.9678

Table 6.3.3-3: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.8266	0.8238	0.8249
	0.9609	0.9602	0.9623
i	0.9674	0.9673	0.9683
1.0	0.8266	0.8238	0.8249
J	0.9609	0.9602	0.9623
	0.9674	0.9673	0.9683
2.0	0.8268	0.8238	0.8249
1	0.9610	0.9602	0.9623
1	0.9675	0.9674	0.9684

Table 6.3.3-4: Variation of expected error

Assad Obs.		bs. error,	
err, winds	5.0	10.0	20.0
0.5	0.7810	0.7818	0.7940
	0.9626	0.9612	0.9624
1	0.9692	0.9687	0.9689
1.0	0.7810	0.7818	0.7940
	0.9626	0.9612	0.9624
	0.9692	0.9687	0.9689
2.0	0.7812	0.7819	0.7940
	0.9627	0.9613	0.9624
	0.9692	0.9687	0.9689

Table 6.3.4-3: Variation of expected error

Assmd Obs.	Assumed 5.0	Obs. error,	heights 20.0
0.5	0.7787	0.7775	0.7845
	0.9621	0.9610	0.9628
	0.9686	0.9684	0.9691
1.0	0.7787	0.7775	0.7845
ĺ	0.9622	0.9610	0.9627
	0.9686	0.9683	0.9691
2.0	0.7789	0.7776	0.7846
i	0.9623	0.9611	0.9628
Į.	0.9687	0.9684	0.9691

Table 6.3.4-4: Variation of expected error

Assud Obs. err, Vinds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.8047	0.8001	0.7985
1	0.9668	0.9667	0.9684
	0.9733	0.9734	0.9743
1.0	0.8030	0.7983	0.7967
- 1	0.9664	0.9662	0.9679
i	0.9724	0.9729	0.9739
2.0	0.7984	0.7930	0.7912
	0.9653	0.9647	0.9663
	0.9717	0.9717	0.9727

Table 6.3.4-5: Variation of expected error

Assed Obs. err, winds	Assumed 5.0	Obs. error, 10.0	heights 20.0
0.5	0.6957	0.6980	0.7169
	0.9403	0.9370	0.9387
	0.9536	0.9524	0.9522
1.0	0.6960	0.6983	0.7172
	0.9405	0.9372	0.9388
	0.9538	0.9525	0.9523
2.0	0.6972	0.6995	7.7184
	0.9412	0.9379	0.9394
	0.9544	0.9531	0.9529

Table 6.3.5-4: Variation of expected error

Assmd Obs. err, winds	Assumed Obs. error, height			
	5.0	10.0	20.0	
0.5	0.6842	0.6824	0.6925	
	0.9328	0.9307	0.9332	
	0.9473	0.9469	0.9479	
1.0	0.6843	0.6824	0.6924	
	0.9329	0.9306	0.9331	
	0.9473	0.9468	0.9478	
2.0	0.6852	0.6828	0.6926	
	0.9338	0.9310	0.9334	
	0.9477	0.9471	0.9481	

Table 6.3.5-5: Variation of expected error

## APPENDIX 2: SUBROUTINE TCOR

This appendix contains the listing for the subroutine that evaluates the true covariance and cross-covariance function values between a given (grid) point and the observation points.

```
SUBROUTINE TCOR(NCF, THD, PHD, NH, TUD, PUD, NU, TVD, PVD, NV, TD, PD, KH, KU,
     1 KV, VAR, CAPPA, CVM, NCVM)
C
C
      THIS SUBROUTINE CALCULATES THE TRUE COVARIANCE BETWEEN THE
C
      OBSERVATION VARIABLES AND INDICATED VARIABLES AT A GIVEN POINT
C
C
      THE ARGUMENTS ARE
C
C
      INPUT ARGUMENTS
C
                   - COVARIANCE FUNCTION NUMBER
      NCF
C
                   - ARRAY OF HEIGHT OBSERVATION LOCATIONS, NH OF THEM
      THD, PHD; NH
C
                   - ARRAY OF U-WIND OBSERVATION LOCATIONS, NU OF THEM
      TUD, PUD; NU
C
                   - ARRAY OF V-WIND OBSERVATION LOCATIONS, NV OF THEM
      TVD, PVD; NV
C
                     THE ABOVE ARE IN DEGREES, LONGITUDE AND LATITUDE,
C
                     RESPECTIVELY
C
                    - NONZERO IF H COVARIANCE TO BE COMPUTED
      KH
C
                   - NONZERO IF U COVARIANCE TO BE COMPUTED
      KU
C
      KV
                   - NONZERO IF V COVARIANCE TO BE COMPUTED
C
                   - VARIANCE OF HEIGHT-HEIGHT ERRORS
      VAR
C
      CAPPA
                   - CORIOLIS CONSTANT
C
      TD,PD
                   - GIVEN (GRID) LOCATION, DEGREES
C
      NCVM
                   - ROW DIMENSION OF CVM ARRAY
C
C
      OUTPUT ARGUMENT
C
                   - ARRAY OF COVARIANCES BETWEEN OBS VARS AND GRID LOCS
      CVM
C
                      AN NH+NU+NV BY 3 ARRAY
C
      IMPLICIT REAL*8 (A-H,O-Z)
      PARAMETER (NSZ=36)
      DIMENSION THD(NH), PHD(NH), TUD(NU), PUD(NU), TVD(NV), PVD(NV),
     1 CVM(NCVM,3)
      DIMENSION TOH(NSZ), POH(NSZ), TOU(NSZ), POU(NSZ), TOV(NSZ), POV(NSZ)
      DIMENSION AP(5), AAP(5)
      COMMON /IO/KOUT
      DATA NTIME/0/
      DATA AP, AAP/5D-6, 3.0825D-6, 3.0825D-6, 3.0825D-6, 2.188D-6,
     1 0D0,0D0,.15D0,.2722D0,.2722D0/
C
C
      THIS ROUTINE IS SET UP TO ACCEPT GENERAL (ISOTROPIC) COVARIANCE
C
      FUNCTIONS. THIS REQUIRES THE DEFINITION OF A NUMBER OF ARITHMETIC
C
      STATEMENT FUNCTIONS WHICH DEFINE THE DISTANCE FUNCTION IN TERMS OF
C
      LATITUDE AND LONGITUDE (PHI AND THETA), ITS DERIVATIVES WRT PHI AN
      THETA, AS WELL AS THE COVARIANCE FUNCTION AND IT'S DERIVATIVES.
C
C
C
      THE FUNCTIONS NEEDED ARE
      DIST
              - DISTANCE FUNCTION
```

```
C
      COV
              - ISOTROPIC COVARIANCE FUNCTION AS A FUNCTION OF DISTANCE
C
      DCOV
              - DERIVATIVE OF COV WRT DISTANCE
C
      D2COV
              - 2ND DERIVATIVE OF COV WRT DISTANCE - DCOV/DISTANCE
C
      VARU
              - VARIANCE OF U-WIND
C
              - VARIANCE OF V-WIND
      VARV
C
              - PARTIAL DIST WRT PHII
      DSDP
C
              - PARTIAL DIST WRT THETAI
      DSDT
C
              - PART OF 2ND PARTIAL DIST WRT PHII AND PHIJ
      DDP1
C
              - PART OF 2ND PARTIAL DIST WRT THETAI AND THETAJ
      DDP2
C
      DDP3
              - PART OF 2ND PARTIAL DIST WRT PHIL AND THETAJ
C
      DATA RAD/6.372D6/
      DIST(P,P1,T,T1)=RAD*DSQRT((P-P1)**2+((T-T1)*COS((P+P1)/2.D0))**2)
      COV(S) = VAR*(OMAA*(1.D0+A*S)*EXP(-A*S)+AA)
      DCOV(S) = -VAR*OMAA*A*A*S*EXP(-A*S)
      D2COV(S) = VAR*OMAA*A**3*S*EXP(-A*S)
      VARU(P) = VAR*OMAA*(RAD*A)**2
      VARV(P) = VAR*OMAA*(RAD*A*COS(P))**2
      DSDP(P,P1,T,T1,S) = RAD**2/S*(-(T-T1)**2*SIN(P+P1)/4.D0+(P-P1))
      DSDT(P,P1,T,T1,S) = RAD**2/S*(T-T1)*COS((P+P1)/2.D0)**2
      DDP1(P,P1,T,T1,S) = RAD**2/S*(1.D0 + (T-T1)**2*COS(P+P1)/4.D0)
      DDP2(P,P1,T,T1,S) = (RAD*COS((P+P1)/2.D0))**2/S
      DDP3(P,P1,T,T1,S) = RAD**2/S*(T-T1)*SIN(P+P1)/2.D0
      IF(NTIME.NE.NCF) THEN
      SET PARAMETERS FOR THIS FUNCTION NUMBER
C
        NCFR=MAX(1,NCF)
        NCFR=MIN(NCFR,5)
        A = AP(NCFR)
        AA = AAP(NCFR)
        OMAA = 1.D0-AA
        WRITE(KOUT, 1)A, AA
        PI=DATAN(1.D0)*4.D0
        DTR = PI/180.D0
        NTIME = NCF
      ENDIF
C
C
      CONVERT LOCATIONS TO RADIANS
C
      DO 100 I=1,NH
        POH(I) = PHD(I)*DTR
        TOH(I) = THD(I)*DTR
  100 CONTINUE
      DO 110 I=1,NU
        POU(I) = PUD(I)*DTR
        TOU(I) = TUD(I)*DTR
  110 CONTINUE
      DO 120 I=1,NV
        POV(I) = PVD(I)*DTR
        TOV(I) = TVD(I)*DTR
  120 CONTINUE
      P = PD*DTR
      T = TD*DTR
C
```

```
START CALCULATIONS
C
      K = 0
      SP = SIN(P)
      CP = COS(P)
      IF(NH.NE.O) THEN
         DO 200 I=1,NH
           K = K + 1
           S = DIST(P, POH(I), T, TOH(I))
           DF = DCOV(S)
           IF(KH.GT.0) CVM(K,1) = COV(S)
           CVM(K,2) = 0.D0
           CVM(K,3) = 0.D0
           IF(KU.GT.0 .AND. S.GT.0.D0)
             CVM(K,2) = DF*DSDP(P,POH(I),T,TOH(I),S)
     1
           IF(KV.GT.O .AND. S.GT.O.DO)
             CVM(K,3) = DF*DSDT(P,POH(I),T,TOH(I),S)
     1
           CVM(K,2) = -CVM(K,2)*CAPPA/SP
           CVM(K,3) = CVM(K,3)*CAPPA/CP/SP
         CONTINUE
  200
      ENDIF
      IF(NU.NE.O) THEN
         DO 220 I=1,NU
           K = K + 1
           S = DIST(P, POU(I), T, TOU(I))
           DF = DCOV(S)
           DD2 = D2COV(S)
           SPI = SIN(POU(I))
           CPI = COS(POU(I))
           CVM(K,1) = 0.D0
           IF(KH.GT.0 .AND. S.GT.0.D0)
              CVM(K,1) = DF*DSDP(POU(I),P,TOU(I),T,S)
     1
           CVM(K,2) = VARU(P)
            IF(KU.GT.0 .AND. S.GT.0.D0)
              CVM(K,2) = \neg DF*DDP1(POU(I),P,TOU(I),T,S) +
     1
               DD2*DSDP(P,POU(I),T,TOU(I),S)*DSDP(POU(I),P,TOU(I),T,S)
     2
            CVM(K,3) = 0.D0
            IF(KV.GT.0 .AND. S.GT.0.D0)
            CVM(K,3) = -DF*DDP3(P,POU(I),T,TOU(I),S) +
     1
              DD2*DSDP(POU(I),P,TOU(I),T,S)*DSDT(P,POU(I),T,TOU(I),S)
     2
             CVM(K,1) = -CVM(K,1)*CAPPA/SPI
             CVM(K,2) = CVM(K,2)*CAPPA**2/SP/SPI
             CVM(K,3) = -CVM(K,3)*CAPPA**2/SP/CP/SPI
          CONTINUE
  220
      ENDIF
       IF(NV.GT.O) THEN
          DO 240 I=1,NV
            K = K + 1
            S = DIST(P, POV(I), T, TOV(I))
            DF = DCOV(S)
            DD2 = D2COV(S)
            SPI = SIN(POV(I))
            CPI = COS(POV(I))
            CVM(K,1) = 0.D0
            IF(KH.GT.0 .AND. S.GT.0.D0)
```

```
CVM(K,1) = DF*DSDT(POV(I),P,TOV(I),T,S)
   1
         CVM(K,2) = 0.D0
         IF(KU.GT.0 .AND. S.GT.0.D0)
           CVM(K,2) = -DF*DDP3(POV(I),P,TOV(I),T,S) +
   2
            DD2*DSDP(P,POV(I),T,TOV(I),S)*DSDT(POV(I),P,TOV(I),T,S)
         CVM(K,3) = VARV(P)
         IF(KV.GT.0 .AND. S.GT.0.D0)
   1
            CVM(K,3) = -DF*DDP2(P,POV(I),T,TOV(I),S) +
             DD2*DSDT(POV(I),P,TOV(I),T,S)*DSDT(P,POV(I),T,TOV(I),S)
   2
         CVM(K,1) = CVM(K,1)*CAPPA/CPI/SPI
         CVM(K,2) = -CVM(K,2)*CAPPA**2/CPI/SPI/SP
         CVM(K,3) = CVM(K,3)*CAPPA**2/CPI/CP/SP/SPI
240
       CONTINUE
    ENDIF
    RETURN
  1 FORMAT(' TCOR - 01/12/90: 2ND AR, A,AA = ',1P,2E11.3)
    END
```

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